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R+D+i for a Sustainable Development

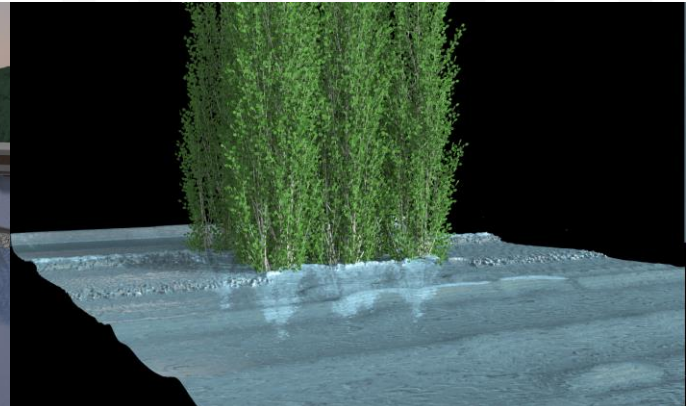
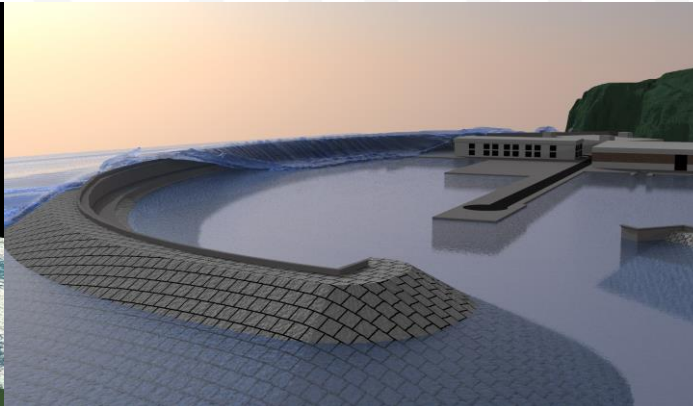
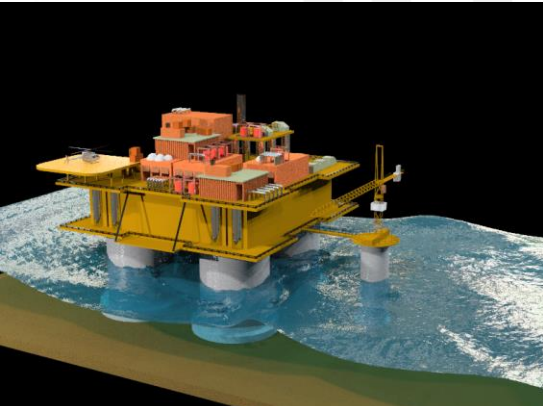
(Beginners Course)



IHFOAM applied to Coastal Engineering

Breaking solitary waves on a mild slope (2D)

Gabriel Barajas, Javier L. Lara, María Maza



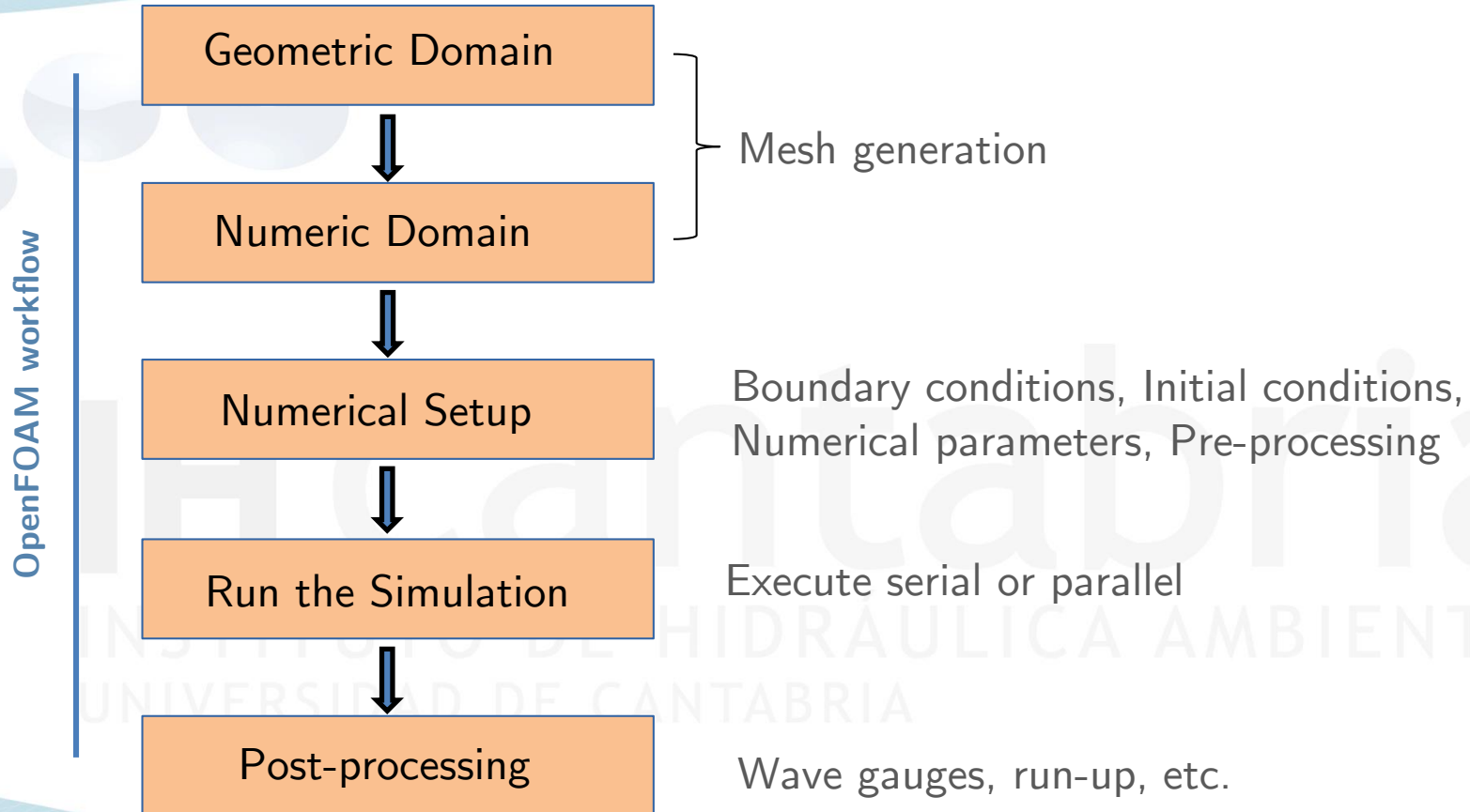
- Now we are going to create a 3D case from a 2D one:
 - Copy a 2D case and change the folder name:

```
$ cp -r ~/OpenFOAM-v1812/tutorials/multiphase/interFoam/laminar/  
waveExampleSolitary ~/IHFoamCourse/.
```
- Rename the case:
 - Rename the case:

```
$ mv ~/IHFoamCourse/waveExampleStokesV ~/IHFoamCourse/synolakis
```
 - Set OpenFOAM environment:

```
$ source ~/OpenFOAM/OpenFOAM-v1812/etc/bashrc
```
 - Ensure everything you don't need is deleted

```
$ cd ~/IHFoamCourse/synolakis  
$ ./Allclean
```

OpenFOAM case

0

- alpha.water
- p_rgh
- U
- k
- epsilon
- nut

constant

- g
- transportProperties
- turbulenceProperties
- waveProperties

system

- blockMeshDict
- setFieldsDict
- snappyHexMeshDict
- extrudeMeshDict
- fvSchemes
- fvSolution
- decomposeParDict
- controlDict

- Update *system/blockMeshDict* to fit the laboratory set-up (synolakis 1986):

```
convertToMeters 1;  
  
vertices  
(  
    ( 0 0.0 0.0)  
    ( 10.0 0.0 0.0)  
    ( 10.0 0.01 0.0)  
    ( 0 0.01 0.0)  
    ( 0.0 0.0 1.0)  
    ( 10.0 0.0 1.0)  
    ( 10.0 0.01 1.0)  
    ( 0.0 0.01 1.0)  
);  
  
blocks  
(  
    hex (0 1 2 3 4 5 6 7) (2000 1 200) simpleGrading (1 1 1)  
);
```

- Create the base mesh:
\$ blockMesh
- Check the base mesh quality:
\$ checkMesh

- In the **0.org** folder, display the VoF (***alpha.water***), the velocity (***U***) and the pressure (***p_rgh***) files :

alpha.water
U
p_rgh

```
dimensions      [0 0 0 0 0 0];
internalField    uniform 0;

boundaryField
{
    inlet
    {
        type      waveAlpha;
        value      uniform 0;
    }
    outlet
    {
        type      zeroGradient;
    }
    ground
    {
        type      zeroGradient;
    }
    sides
    {
        type      empty;
    }
    top
    {
        type      inletOutlet;
        inletValue uniform 0;
        value      uniform 0;
    }
}
```

```
dimensions      [0 1 -1 0 0 0];
internalField    uniform (0 0 0);

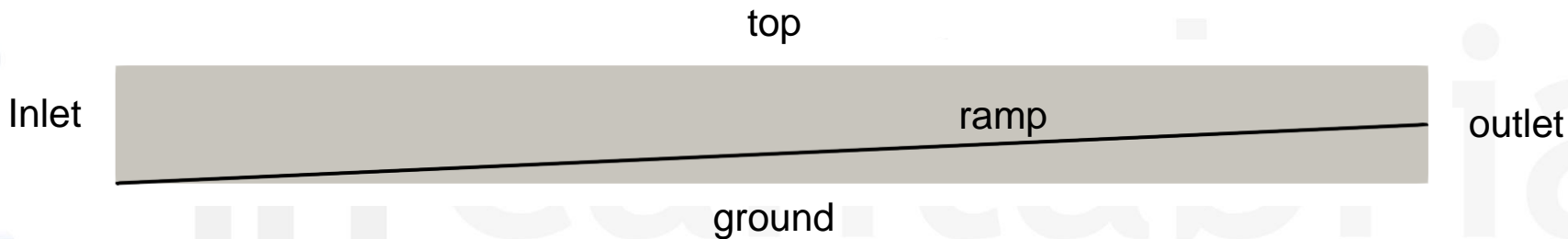
boundaryField
{
    inlet
    {
        type      waveVelocity;
        value      uniform (0 0 0);
    }
    outlet
    {
        type      waveVelocity;
        value      uniform (0 0 0);
    }
    sides
    {
        type      empty;
    }
    ground
    {
        type      fixedValue;
        value      uniform (0 0 0);
    }
    top
    {
        type      pressureInletOutletVelocity;
        value      uniform (0 0 0);
    }
}
```

```
dimensions      [1 -1 -2 0 0 0];
internalField    uniform 0;

boundaryField
{
    inlet
    {
        type      fixedFluxPressure;
        value      uniform 0;
    }
    outlet
    {
        type      fixedFluxPressure;
        value      uniform 0;
    }
    ground
    {
        type      fixedFluxPressure;
        value      uniform 0;
    }
    sides
    {
        type      empty;
    }
    top
    {
        type      totalPressure;
        p0         uniform 0;
    }
}
```

- Define and create a mild slope (using Autocad, Rhino, etc.).
- Check the .stl file; open Paraview, load the .stl file and check that the geometry fits the base mesh:

```
$ touch ih.foam && paraview
```



- Update the case to take into account the new geometry:

```
$ mkdir constant/triSurface  
$ cp ramp.stl constant/triSurface/.
```


- Using ***snappyHexMesh***, as mesh generator to take the existing base mesh and remesh it to fit the real geometry of the experiments.
- Copy snappyHexMeshDict from a tutorial:

```
$ cp -r ~/OpenFOAM-v1806/tutorials/multiphase/interFoam/RAS/mixerVesselAMI/system/  
snappyHexMeshDict ~/IHFoamCourse/overSetWaves/system/.
```
- This intermediate mesh, is created from the dictionary ***system/snappyHexMeshDict***:
 - ***CastellatedMesh***:
 - Mesh Refinement in prescribed regions.
 - Detection of the domain (surface and volume).
 - Removal of cells outside the domain.
 - ***Snap***:
 - Mesh morphing to follow the provided geometry.
 - Layer addition could also be done.

```
// Which of the steps to run  
castellatedMesh true;  
snap true;  
addLayers false;
```

```
geometry
{
  ramp.stl
  {
    type triSurfaceMesh;
    name ramp;
  }
}
```

→ Definition of the a new boundary (mesh refinement and removal of cells around it).

```
nCellsBetweenLevels 3;
```

→ Minimum number of cells before going to the next level of resolution (Number of buffer layers between different levels.)

```
features
(
);
```

→ List of feature edges, that describe Sharp cornes, for refinement.

```
refinementSurfaces
{
  ramp
  {
    level ( 1 1 );
  }
}
```

→ Surface based refinements, based on two levels for every surface (the first is the minimum level, the second level is the maximum level).

```
refinementRegions
{
}
```



Volume based refinements, based on two levels for every volume (the first is the minimum level, the second level is the maximum level).

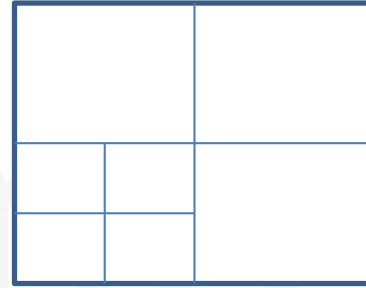
- Refinement levels in OpenFOAM: increase in the refinement level reduces the cell size by half.



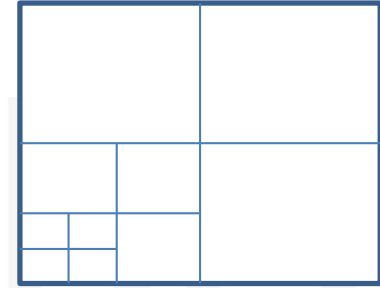
Level 0



Level 1



Level 2



Level 3

```
locationInMesh (0.25 0.001 0.30);
```



Cartesian points (x, y, z) to identify the volumen to retain the final mesh.

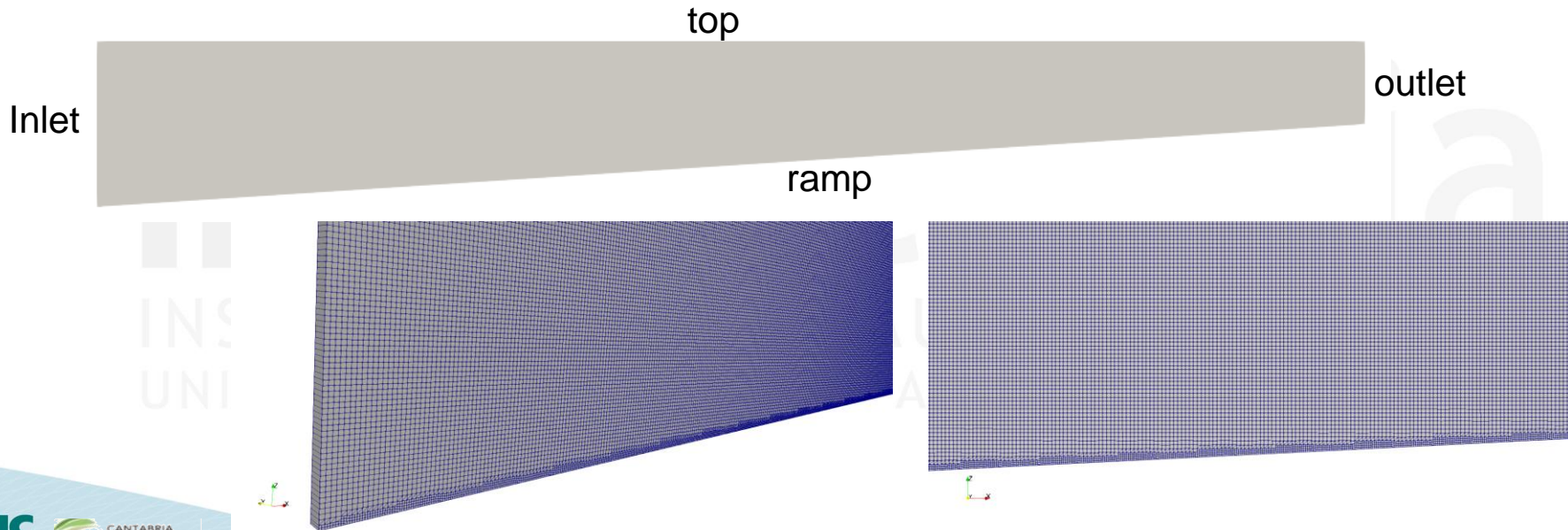
- Create the intermediate mesh:
\$ snappyHexMesh -overwrite.

- Adjust the mesh: as it has been created by **snappyHexMesh** with several cells in the spanwise direction, it must be modified and extrude it to be purely two dimensional (2D).

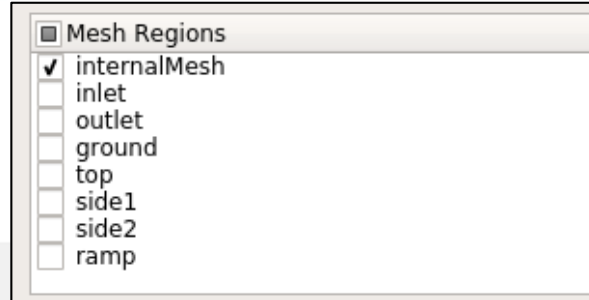
```
constructFrom patch;  
sourceCase ".";  
sourcePatches (side1);  
  
// If construct from patch: patch to use for back (can be same as sourcePatch)  
exposedPatchName side2;  
  
// Flip surface normals before usage.  
flipNormals true;  
  
//- Linear extrusion in point-normal direction  
extrudeModel      linearNormal;  
  
nLayers           1;  
  
expansionRatio    1.0;  
  
linearNormalCoeffs  
{  
    thickness      0.02;  
}  
  
// Do front and back need to be merged? Usually only makes sense for 360  
// degree wedges.  
mergeFaces false;
```

- **sourcePatches**: name of the patch to extrude.
 - **exposedPatchName**: name of the patch opposed to the extruded one (sourcePatches)
 - **nLayers**: number of divisions from sourcePatches to exposedPatchName
 - **thickness**: length of the extrusion.
- Extrude the intermediate mesh:
\$ extrudeMesh
 - Check the final mesh quality:
\$ checkMesh

- Check your final mesh with Paraview:
\$ paraview
- Load the ih.foam file and press “Apply”. (Remember to tick “Skip Zero Time”, as the boundary conditions in the 0 folder have not been updated yet.)



- The final boundaries can be checked with Paraview (in the *Mesh Regions* dialog box) or they can be checked in the *constant/polyMesh/boundary* file.



```

7
(
  inlet
  {
    type            patch;
    nFaces          200;
    startFace       708588;
  }
  outlet
  {
    type            patch;
    nFaces          102;
    startFace       708788;
  }
  ground
  {
    type            wall;
    inGroups        1(wall);
    nFaces          1000;
    startFace       708890;
  }
  top
  {
    type            patch;
    nFaces          2000;
    startFace       709890;
  }
  side1
  {
    type            empty;
    inGroups        1(empty);
    nFaces          710788;
    startFace       711890;
  }
  side2
  {
    type            empty;
    inGroups        1(empty);
    nFaces          0;
    startFace       1422678;
  }
  ramp
  {
    type            wall;
    inGroups        1(wall);
    nFaces          2000;
    startFace       1422678;
  }
)

```

- Once the final boundaries are known, update **0.org** folder:

– alpha.water:

```
ground
{
    type          zeroGradient;
}
```



```
ramp
{
    type          zeroGradient;
}
```

– p_rgh:

```
ground
{
    type          fixedFluxPressure;
    value         uniform 0;
}
```



```
ramp
{
    type          fixedFluxPressure;
    value         uniform 0;
}
```

– U:

```
ground
{
    type          fixedValue;
    value         uniform (0 0 0);
}
```



```
ramp
{
    type          fixedValue;
    value         uniform (0 0 0);
}
```

```
outlet
{
    type          waveVelocity;
    value         uniform (0 0 0);
}
```



```
outlet
{
    type          noSlip;
}
```

- The case is defined as turbulent in:
\$ more constant/turbulenceProperties

```
simulationType  RAS;  
  
RAS  
{  
    RASModel      kEpsilon;  
    turbulence     on;  
    printCoeffs   on;  
}
```

- Therefore, the turbulent kinematic energy (k), the turbulent dissipation (***epsilon***) and the turbulent viscosity (***nut***) variables must be defined and added to the ***0.org*** folder:

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k

```

dimensions      [0 2 -2 0 0 0];
internalField   uniform 0.0084;

boundaryField
{
    inlet
    {
        type      zeroGradient;
    }
    outlet
    {
        type      zeroGradient;
    }
    side1
    {
        type      empty;
    }
    side2
    {
        type      empty;
    }
    ground
    {
        type      kqRWallFunction;
        value      uniform 0.0084;
    }
    ramp
    {
        type      kqRWallFunction;
        value      uniform 0.0084;
    }
    top
    {
        type      inletOutlet;
        inletValue uniform 0.0084;
        value      uniform 0.0084;
    }
}

```

epsilon

```

dimensions      [0 2 -3 0 0 0];
internalField   uniform 0.0005094;

boundaryField
{
    inlet
    {
        type      zeroGradient;
    }
    outlet
    {
        type      zeroGradient;
    }
    side1
    {
        type      empty;
    }
    side2
    {
        type      empty;
    }
    ground
    {
        type      epsilonWallFunction;
        value      uniform 0.0005094;
    }
    ramp
    {
        type      epsilonWallFunction;
        value      uniform 0.0005094;
    }
    top
    {
        type      inletOutlet;
        inletValue uniform 0.0005094;
        value      uniform 0.0005094;
    }
}

```

nut

```

dimensions      [0 2 -1 0 0 0];
internalField   uniform 0;

boundaryField
{
    inlet
    {
        type      calculated;
        value      uniform 0;
    }
    outlet
    {
        type      calculated;
        value      uniform 0;
    }
    side1
    {
        type      empty;
    }
    side2
    {
        type      empty;
    }
    ground
    {
        type      nutkWallFunction;
        value      uniform 0;
    }
    ramp
    {
        type      nutkWallFunction;
        value      uniform 0;
    }
    top
    {
        type      calculated;
        value      uniform 0;
    }
}

```

- Update the wave conditions in ***constant/waveProperties***:
 - ***WaveModel***: Boussinesq solitary wave
 - ***nPaddle***: 1 single wave paddle (2d)
 - ***waveHeight***: $H = 0.07$ m.
 - ***activeAbsorption***: no (absorption yes/no at generation)

```
inlet
{
    alpha            alpha.water;
    waveModel        Boussinesq;
    nPaddle          1;
    waveHeight        0.07;
    waveAngle         0.0;
    rampTime          0.0;
    activeAbsorption  no;
    wavePeriod        0.0;
}
```

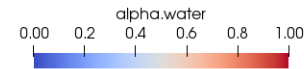
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- Update the initial set-up in *system/setFieldsDict*:

```
defaultFieldValues
(
    volScalarFieldValue alpha.water 0
);

regions
(
    boxToCell
    {
        box (-1.0 -1.0 -1.0) (10.0 1.0 0.25);
        fieldValues
        (
            volScalarFieldValue alpha.water 1
        );
    }
);
```

- \$ cp -r 0.org 0
- \$ setFields
- Open Paraview and plot the initial set-up to ensure everything is correct:
\$ paraview



- Water and air properties are defined in:
\$ more constant/transportProperties

```
phases (water air);

water
{
    transportModel    Newtonian;
    nu                [0 2 -1 0 0 0 0] 1e-06;
    rho               [1 -3 0 0 0 0 0] 1000;
}

air
{
    transportModel    Newtonian;
    nu                [0 2 -1 0 0 0 0] 1.48e-05;
    rho               [1 -3 0 0 0 0 0] 1;
}

sigma               [1 0 -2 0 0 0 0] 0.07;
```

- Gravity is defined in:
\$ more constant/g

```
dimensions    [0 1 -2 0 0 0 0];
value        ( 0 0 -9.81 );
```

Numerical Schemes:

- **system/fvSchemes:** is the file that sets the numerical scheme for the different terms.

```

ddtSchemes
{
  default      Euler;
}

gradSchemes
{
  default      Gauss linear;
}

divSchemes
{
  div(rhoPhi,U)  Gauss linearUpwind grad(U);
  div(phi,alpha) Gauss vanLeer;
  div(phiRb,alpha) Gauss linear;
  div(((rho*nuEff)*dev2(T(grad(U))))) Gauss linear;

  div(phi,k)      Gauss upwind;
  div(phi,epsilon) Gauss upwind;
}
  
```

Temporal discretization (**Euler** is a first order implicit discretisation scheme).

Gradient derivative terms, that is surface normal gradient terms (**Gauss linear** is second order discretisation scheme)

Divergence terms, such as advection terms and other terms that are often diffusive in nature (**Gauss linearUpwind grad(U)** is second order, **Gauss vanLeer** is second order and **Gauss upwind** is a first order numerical scheme)

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Numerical Schemes:

```
laplacianSchemes
{
  default      Gauss linear limited 0.5;
}

interpolationSchemes
{
  default      linear;
}

snGradSchemes
{
  default      limited 0.5;;
}
```

Laplacian terms, such as the diffusion term in the momentum equation (**Gauss linear limited** is second order accuracy, values between 0 and 1 to handle a non-orthogonal mesh)

Cell to face interpolations of values (**linear** is second order discretisation scheme)

Component of gradient normal to a cell face (**limited** is second order accuracy, values between 0 and 1 to handle a non-orthogonal mesh)

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Algorithm control:

- In *system/fvSolutions* are defined the equations solvers, tolerances and algorithms.
- Controls for **MULES**, solver of the VoF equation:
 - **nAlphaCorr**: loops over VoF equation
 - **nAlphaSubcycles**: number of sub-cycles within the VoF equation
 - **cAlpha**: artificial compression velocity.

```
solvers
{
    "alpha.water.*"
    {
        nAlphaCorr      1;
        nAlphaSubCycles 3;
        cAlpha          1;
    }
}
```

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Algorithm control:

- For each variable solved in the particular equation, the type of solver and parameters that are used by the solver must be defined.
- Normally, the last iteration (variables are solved multiple times within a solution step) is solved with different parameters.

```
pcorr
{
    solver          PCG;
    preconditioner   DIC;
    tolerance        1e-6;
    relTol           0.1;
}
pcorrFinal
{
    solver          PCG;
    preconditioner   DIC;
    tolerance        1e-7;
    relTol           0;
}
p_rgh
{
    solver          PCG;
    preconditioner   DIC;
    tolerance        1e-6;
    relTol           0.1;
}
p_rghFinal
{
    solver          PCG;
    preconditioner   DIC;
    tolerance        1e-7;
    relTol           0;
}
"(U|k|epsilon)"
{
    solver          PBiCG;
    preconditioner   DILU;
    tolerance        1e-6;
    relTol           0.1;
}
"(U|k|epsilon)UFinal"
{
    solver          PBiCG;
    preconditioner   DILU;
    tolerance        1e-7;
    relTol           0;
}
```

Algorithm control:

- **PIMPLE** algorithm solves the pressure-velocity coupling in the Navier-Stokes equations.
- **PIMPLE** algorithm combines PISO and SIMPLE.
 - **momentumPredictor**: switch the control for solving the momentum predictor.
 - **nCorrectors**: number of times the algorithm solves the pressure equation and momentum corrector in each step
 - **nOrthogonalCorrectors**: specifies repeated solutions of the pressure equation, used to update the explicit non-orthogonal correction.

```
PIMPLE
{
    momentumPredictor no;
    nCorrectors      2;
    nNonOrthogonalCorrectors 0;
}
```

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- Define simulation parameters in ***system/controlDict***
 - Solver: ***interFoam*** (incompressible two phase flow)
 - startTime*** (start time for the simulation), ***endTime*** (end time for the simulation), ***deltaT*** (time step of the simulation).
 - writeInterval*** (controls the timing of write output), ***purgeWrite*** (integer representing a limit on the number of time directories that are stored).
 - maxCo*** (maximum Courant Number), ***maxAlphaCo*** (maximum Courant number for the phase fields), ***maxDeltaT*** (upper limit of the time step).

```

application      interFoam;

startFrom        latestTime;

startTime        0;

stopAt           endTime;

endTime          20.0;

deltaT           0.01;

writeControl     adjustableRunTime;

writeInterval    0.1;

purgeWrite       0;

writeFormat      ascii;

writePrecision   6;

writeCompression off;

timeFormat       general;

timePrecision    6;

runTimeModifiable yes;

adjustTimeStep   yes;

maxCo            0.65;
maxAlphaCo       0.65;
maxDeltaT        0.05;
  
```

- Update the runtime postprocessing sensors (*system/controlDict*)
 - to get the iso-Surface of the free surface elevation:

```
functions
{
    freeSurface
    {
        type surfaces;
        functionObjectLibs
        (
            "libsampling.so"
        );
        writeControl outputTime;
        outputInterval 1;
        surfaceFormat stl;
        interpolationScheme cellPoint;
        surfaces
        (
            topFreeSurface
            {
                type isoSurface;
                isoField alpha.water;
                isoValue 0.5;
                interpolate true;
            }
        );
        fields
        (
            alpha.water
        );
    }
}
```

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- Update the runtime postprocessing sensors (*system/controlDict*)
 - to get the free surface at some specific positions along the domain.

```
line
{
    type            sets;
    libs            ("libsampling.so");
    enabled          true;
    writeControl     writeTime;
    writeInterval    1;

    interpolationScheme cellPoint;
    setFormat        raw;
    sets
    (
        line1
        {
            type      uniform;
            axis       distance;
            start      ( 1.0 1.0 0.0 );
            end        ( 1.0 1.0 0.7 );
            nPoints    1001;
        }
        line2
        {
            type      uniform;
            axis       distance;
            start      ( 2.0 1.0 0.0 );
            end        ( 2.0 1.0 0.7 );
            nPoints    1001;
        }
        line3
        {
            type      uniform;
            axis       distance;
            start      ( 3.0 1.0 0.0 );
            end        ( 3.0 1.0 0.7 );
            nPoints    1001;
        }
    )
}
```

Breaking solitary wave on a mild slope (2D)

```
line4
{
    type      uniform;
    axis       distance;
    start      ( 5.0 1.0 0.0 );
    end        ( 5.0 1.0 0.7 );
    nPoints    1001;
}
line5
{
    type      uniform;
    axis       distance;
    start      ( 7.0 1.0 0.0 );
    end        ( 7.0 1.0 0.7 );
    nPoints    1001;
}
line6
{
    type      uniform;
    axis       distance;
    start      ( 9.0 1.0 0.0 );
    end        ( 9.0 1.0 0.7 );
    nPoints    1001;
}
);

fixedLocations false;
fields
(
    U alpha.water
);
}
```


- Decompose case:
 - ***system/decomposeParDict***: if we want to run our simulation in parallel we can decompose it using this file:
 - ***numberOfSubdomains***: set the number of parts in which we are going to split our domain.
 - ***n***: it should be equal to the number of subdomains

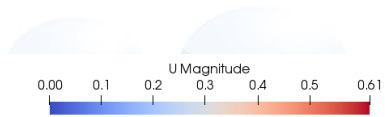
Run the command:

\$ **decomposePar**

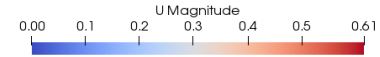
```
numberOfSubdomains 2;  
  
method             hierarchical;  
  
hierarchicalCoeffs  
{  
    n                (2 1 1);  
    delta            0.001;  
    order            xyz;  
}
```

- Run the case!
\$ mpirun -np 2 interFoam -parallel > log.synolakis &
\$ tail -f log.synolakis
\$ kill PID number
- Postprocessing with Paraview:
\$ paraFoam -touch

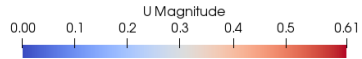
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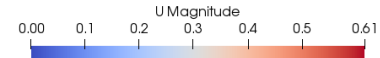
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Time: 3.00 s.



Time: 4.49 s.

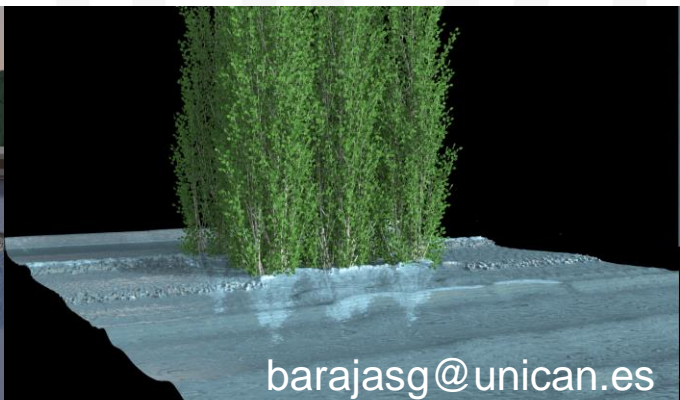
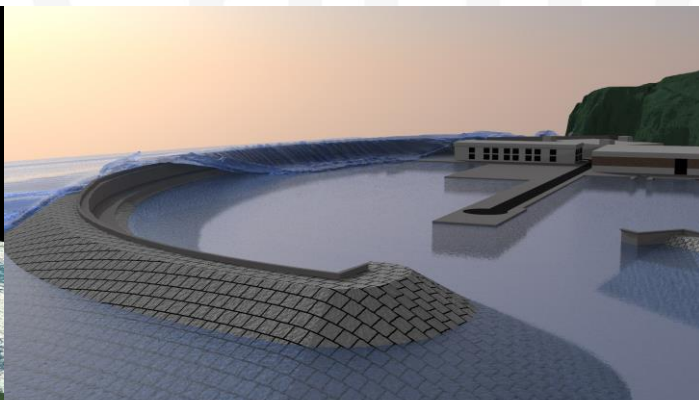
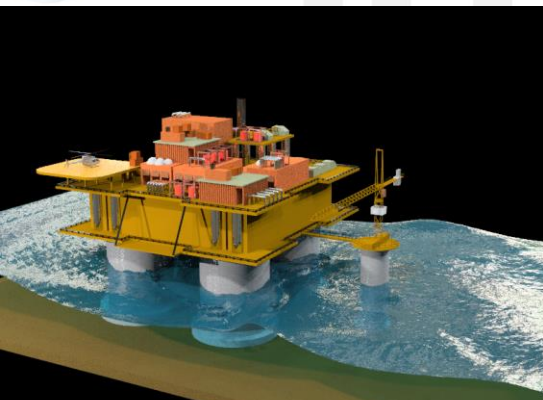


Time: 6.60 s.

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